

Definition:

https://en.wikipedia.org/wiki/Simultaneous_localization_and_mapping

SLAM from a DLZP Group perspective is the ability to use low cost imaging devices to create visuals of the environment and then to classify that data for use by clients in their applications. This can be used for Equipment Tracking and Evaluation, Endangered Species Identification, and Space Use by NASA for the Manned/Unmanned Missions.

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